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Complexity Theory of Polynomial-Time Problems

Lecture 13: Recap, Further Directions, Open Problems

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I. Recap

II. Further Directions

III. Open Problems



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I. Recap



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Hard problems

SAT: given a formula in conj. normal form on n variables
is it satisfiable?

conjecture: no $O(2^{(1-\varepsilon)n})$ algorithm (SETH)

OV: given n vectors in $\{0,1\}^d$ (for small d)
are any two orthogonal?

conjecture: no $O(n^{2-\varepsilon})$ algorithm

APSP: given a weighted graph with n vertices
compute the distance between any pair of vertices

conjecture: no $O(n^{3-\varepsilon})$ algorithm

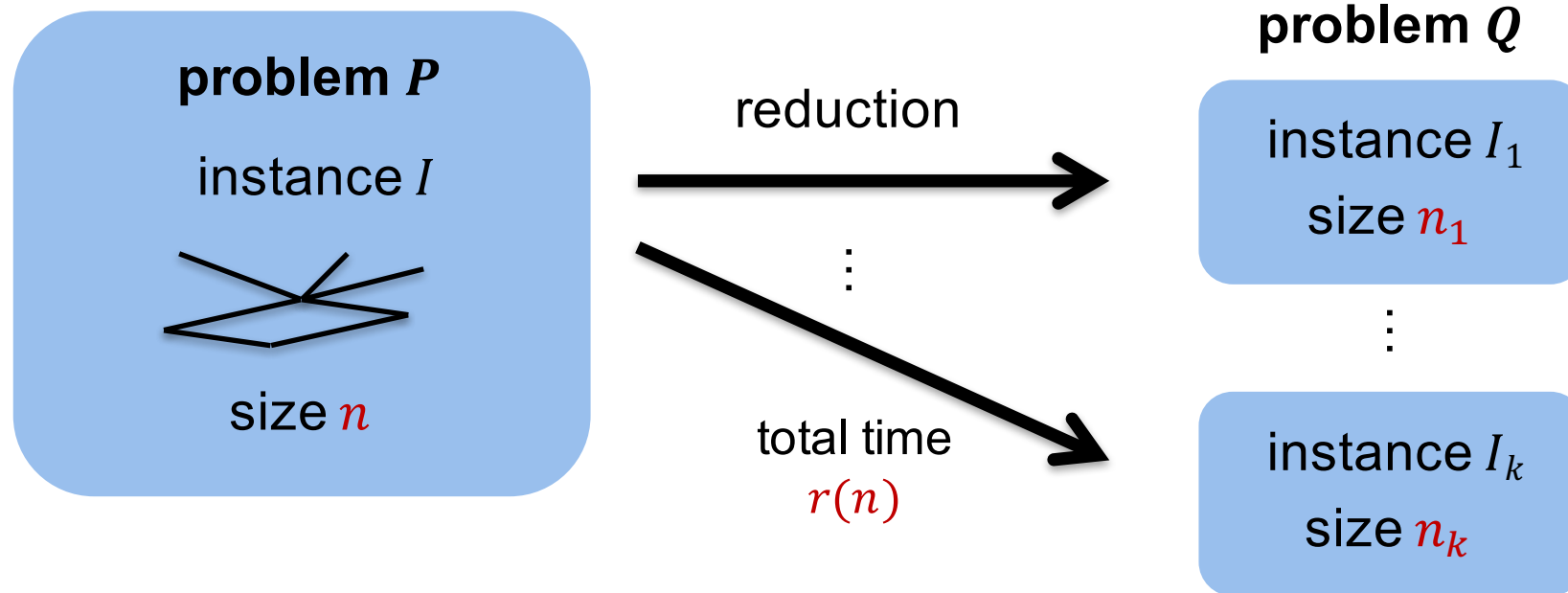
3SUM: given n integers
do any three sum to 0?

conjecture: no $O(n^{2-\varepsilon})$ algorithm



Fine-Grained Reductions

A **fine-grained reduction** from (P, T) to (Q, T') is an algorithm A for P with **oracle** access to Q s.t.:



Properties:

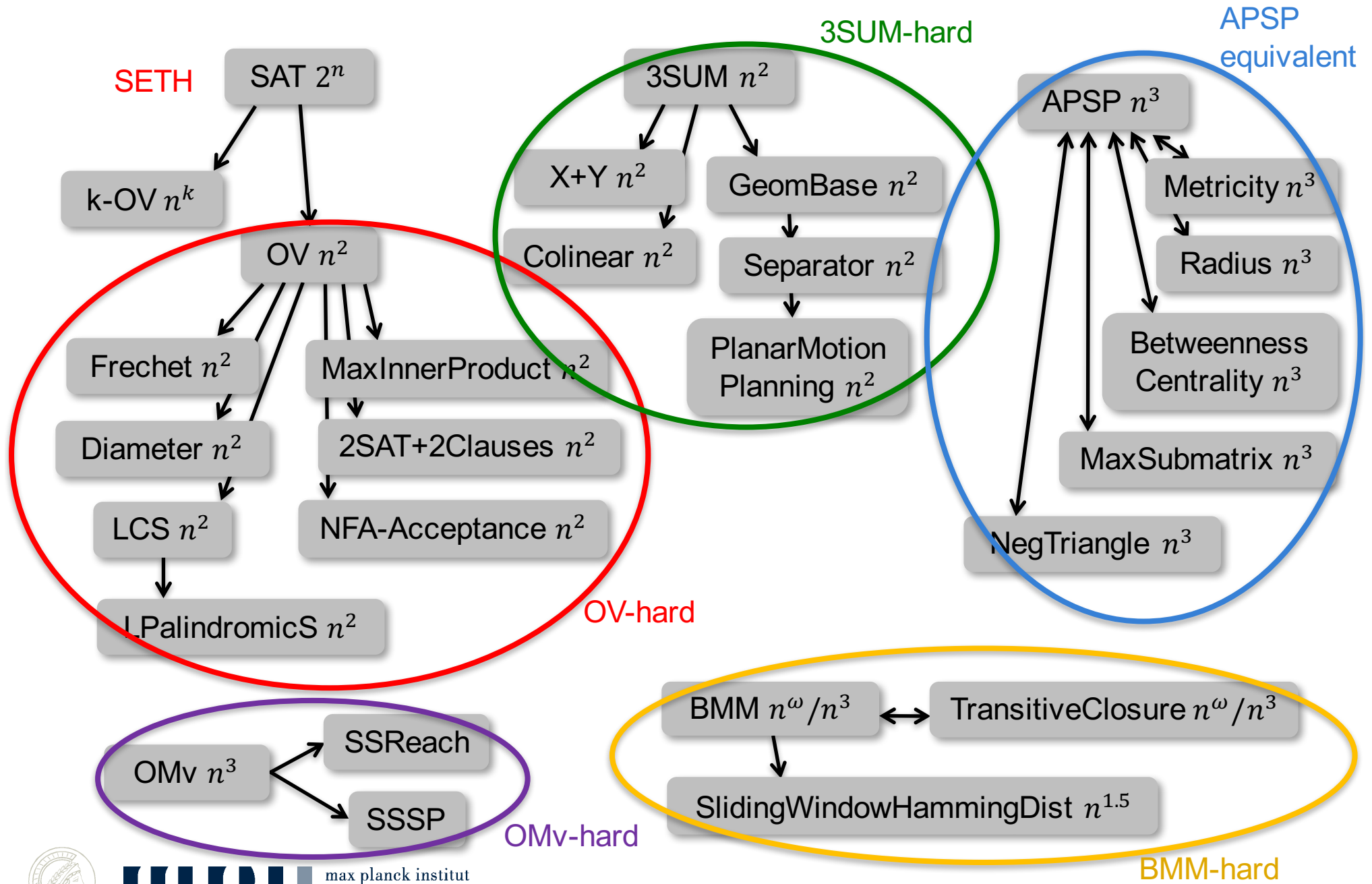
for any instance I , algorithm $A(I)$ correctly solves problem P on I

A runs in time $r(n) = O(T(n)^{1-\gamma})$ for some $\gamma > 0$

for any $\varepsilon > 0$ there is a $\delta > 0$ s.t. $\sum_{i=1}^k T'(n_i)^{1-\varepsilon} \leq T(n)^{1-\delta}$



Complexity Inside P



Conditional Lower Bounds ...

... allow to classify polynomial time problems

... are an analogue of NP-hardness

yield good reasons to stop searching for faster algorithms

should belong to the basic toolbox of theoretical computer scientists

... allow to search for new algorithms with better focus

improve SAT before longest common subsequence

non-matching lower bounds suggest better algorithms

... motivate new algorithms

relax the problem and study approximation algorithms,

parameterized running time, ...



Algorithms

BMM:

fast matrix multiplication: $\omega < 3$

NodeWeightedNegativeTriangle $O(n^\omega)$

k-Clique $O(n^{\omega k/3})$

MaxCut $O(2^{\omega n/3} \text{poly}(n))$

lower order improvements:

4 Russians trick yields log-factor improvements

polynomial method:

OV in $O(n^{2-1/O(\log(d/\log n))})$ or $O(n^2/2^{\Omega(\sqrt{\log n})})$

APSP and OMv in $O(n^3/2^{\Omega(\sqrt{\log n})})$

dynamic graph algorithms:

incremental/decremental/fully dynamic, amortized/worst-case,
update/query time for shortest path and reachability problems



More (Algorithmic) Concepts

Decision Trees:

$\tilde{O}(n^{3/2})$ for 3SUM

(Co-)Nondeterministic Algorithms:

$\tilde{O}(n^{3/2})$ for 3SUM

Nondeterministic SETH

Polynomials and Circuits:

Over the integers, or \mathbb{Z}_p , or AND-OR

polynomial multiplication (FFT!), division, interpolation

multipoint evaluation



Modern Algorithms Philosophy

“Fast Matrix Multiplication and Fast Fourier Transform are the only non-trivial algorithmic tools that we have.”

“Whenever you design an algorithm, try to prove a matching conditional lower bound to show optimality.”



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II. Further Directions

1. Hardness Under Multiple Hypotheses



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Hardness Under Multiple Hypotheses

so far we identified **a reason** for the hardness of some problems

what about **multiple reasons**?

if a problem Q is SETH-hard **and** 3SUM-hard **and** APSP-hard

then it is as hard as it gets

we can forget about improved algorithms any time soon

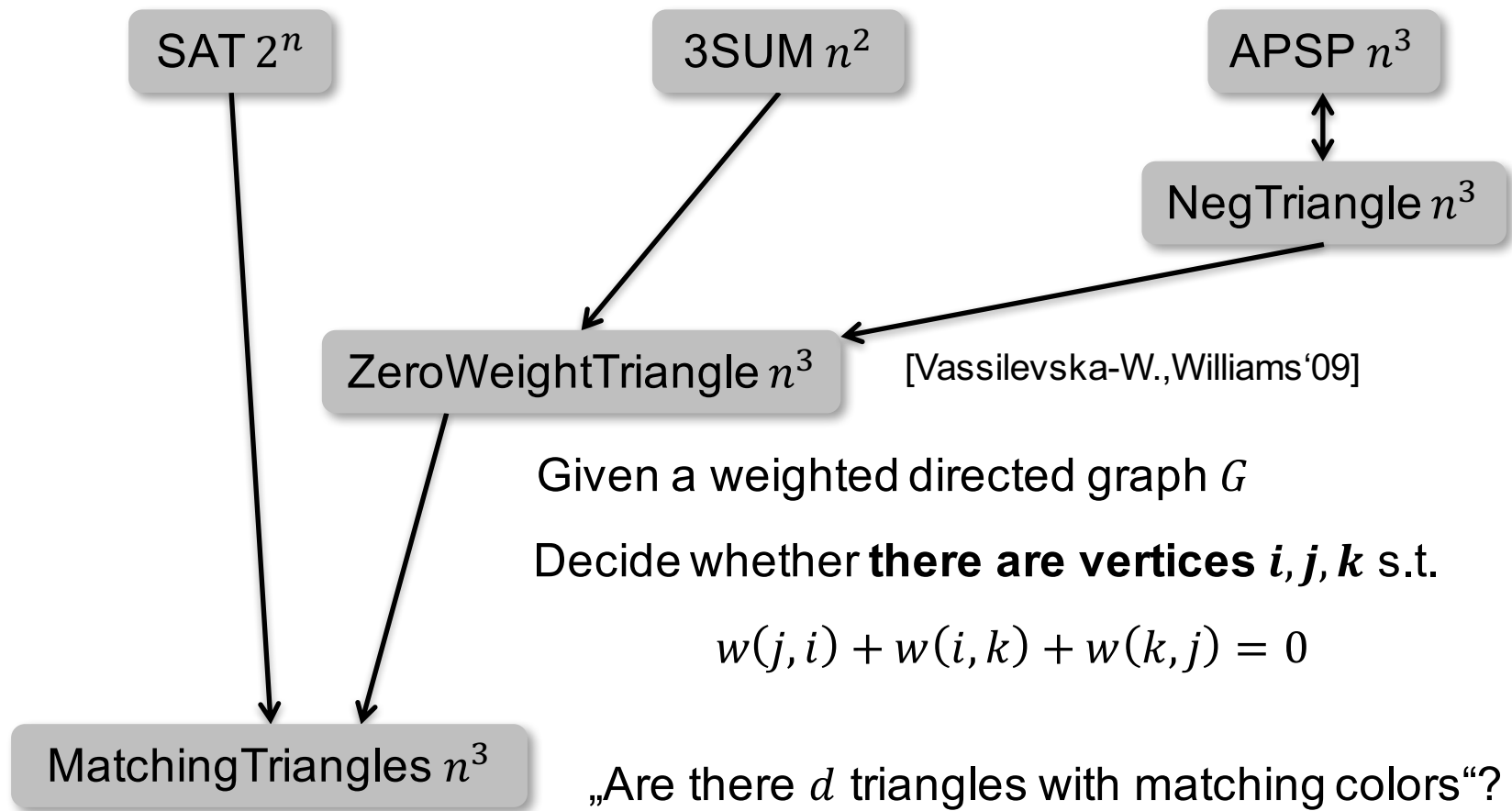
Q is hard under the following weak conjecture:

At least one of SETH or 3SUM-H or APSP-H holds



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Complexity Inside P



Given a weighted directed graph G

Decide whether **there are vertices i, j, k** s.t.

$$w(j, i) + w(i, k) + w(k, j) = 0$$

MatchingTriangles n^3

„Are there d triangles with matching colors“?

Given a directed graph G with colored nodes, and number d

Are there colors a, b, c s.t. G contains at least d triangles (i, j, k) where i has color a , j has color b , and k has color c ?



II. Further Directions

2. Ruling out Superpolylogarithmic Improvements



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Ruling out Superpolylog Improvements

we have seen for Longest Common Subsequence (LCS):

4 Russians trick: $O(n^2 / \log^2 n)$

OV-hardness: lower bound $\Omega(n^{2-\varepsilon})$

does the polynomial method apply?

is LCS in time $n^2 / 2^{\Omega(\sqrt{\log n})}$? or $n^2 / \log^{\omega(1)} n$?

how to rule out superpolylogarithmic improvements?

SETH/OVH are too coarse!

OV has superpolylogarithmic improvements!



SAT

$$F: \{0,1\}^n \rightarrow \{0,1\}$$

Is F satisfiable?

Need $\Omega(2^n)$ queries, unless we analyze F

*Hardness of F -SAT depends
on our ability to analyze F*

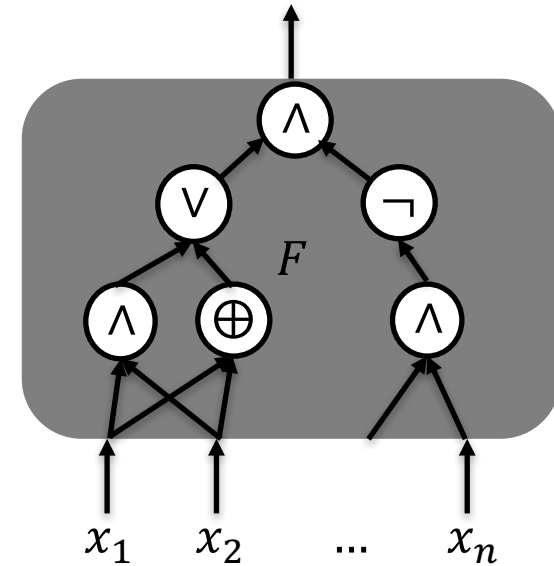
F given by a...

DNF: polytime

CNF: SETH

Turing machine: extremely hard

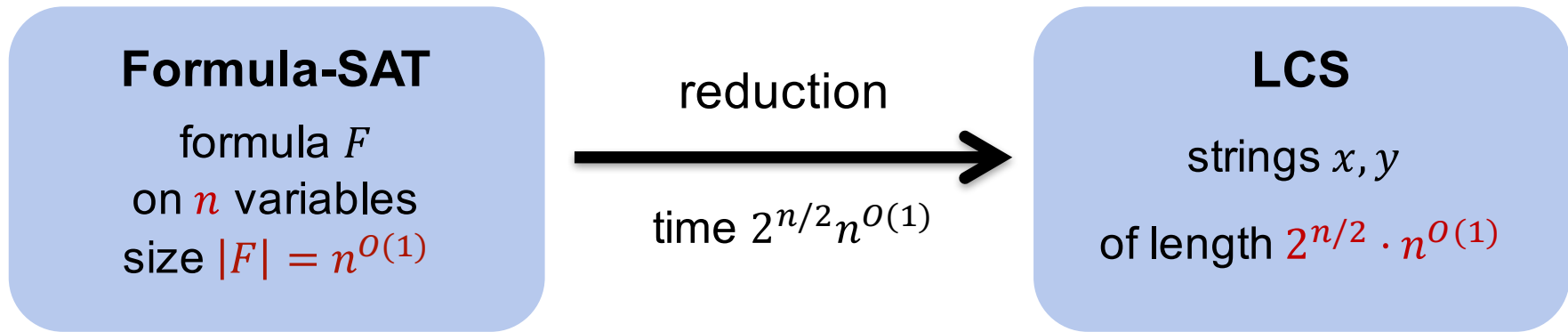
formula: harder than SETH, but still easy to work with



formula = circuit over AND/OR/NOT
(and maybe XOR/...), where every
gate has fanout 1, except for inputs



Formula-SAT Hardness



$2^{(1-\varepsilon/2)n} \cdot n^{O(1)}$ algorithm

\Leftarrow

$O(n^{2-\varepsilon})$ algorithm

$2^n/n^{\omega(1)}$ algorithm

\Leftarrow

$n^2/\log^{\omega(1)}n$ algorithm

no $2^n/n^{\omega(1)}$ algorithm known,
even for $|F| = n^{O(1)}$

Thm: LCS has no $n^2/\log^{\omega(1)}n$ algorithm [Abboud,Hansen,Vassilevska-W,Williams'16]
unless Formula-SAT has an $2^n/n^{\omega(1)}$ algorithm for $|F| = n^{O(1)}$.



II. Further Directions

3. Hardness Classes



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Hardness Classes

the field of „fine-grained complexity“ is very **problem-centric**
everything evolves around hard problems

what about **classes of problems**, as in classic complexity?

can we prove hardness/completeness of a problem for a class
w.r.t. fine-grained reductions?



Hardness Classes

class of **first-order graph properties**:

given a graph G with m edges

given a first-order formula ϕ with $k + 1$ quantifiers

check whether ϕ evaluates to true on G

is in time $O(m^k)$

[Gao, Impagliazzo'16]

e.g. $\exists u \exists v \exists w: E(u, v) \wedge E(v, w) \wedge E(u, w)$

„does G contain a triangle?“

$\forall u \forall v \exists w: E(u, w) \wedge E(w, v)$

„does G have diameter=2?“

Thm: The following are equivalent:

[Gao, Impagliazzo'16]

- $\exists \varepsilon, \delta > 0$: OV in dimension $d \leq n^\delta$ has an $O(n^{2-\varepsilon})$ algorithm (\neg OVH)
- $\forall k \geq 2$: for any first-order formula ϕ with $k + 1$ quantifiers there exists $\varepsilon' > 0$ s.t. ϕ can be decided in time $O(m^{k-\varepsilon'})$ on any given graph with m edges



II. Further Directions

4. Multivariate Analysis



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Multivariate Analysis

LCS is OV-hard: lower bound $\Omega(n^{2-\varepsilon})$

what if $|y| = m \ll n = |x|$? How fast can we compute $LCS(x, y)$?

dynamic programming: $O(nm)$

Parameter Setting $LCS(\beta)$: $(0 \leq \beta \leq 1)$

.. is the LCS problem restricted to strings with $m = \Theta(n^\beta)$

what is the best running time $n^{f(\beta)+o(1)}$ for $LCS(\beta)$ for any β ?

Cor: unless OVH fails, for any β any algorithm for $LCS(\beta)$ takes time

$$\Omega(n) + n^{2\beta-o(1)} = \Omega(n) + m^{2-o(1)}$$

Proof: for any n , $m = \lceil n^\beta \rceil$, for any (binary) strings with $|x'|, |y'| = m - 1$:

$$\begin{array}{llll} x := x' 2^{n-|x'|} & & |x| = n & \text{where } 2 \text{ is a} \\ y := y' 2^{m-|y'|} & \text{with length} & |y| = m & \text{fresh symbol} \end{array}$$



$$LCS(x, y) = LCS(x', y') + \min\{n - |x'|, m - |y'|\}$$

Multivariate Analysis

LCS is OV-hard: lower bound $\Omega(n^{2-\varepsilon})$

what if $|y| = m \ll n = |x|$? How fast can we compute $\text{LCS}(x, y)$?

dynamic programming: $O(nm)$

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$$\Omega(n) + n^{2\beta-o(1)} = \Omega(n) + m^{2-o(1)}$$

Algorithm with time $\tilde{O}(n + m^2)$ exists!

[Hirschberg'77]

LCS differs from other similarity measures that take time $(nm)^{1-o(1)}$

[B.'14, B.,Künnemann'15]



Multivariate Analysis

Multivariate fine-grained complexity

Parameter Setting $LCS(\beta)$: $(0 \leq \beta \leq 1)$

.. is the LCS problem restricted to strings with $m = \Theta(n^\beta)$

what is the best running time $n^{f(\beta)+o(1)}$ for $LCS(\beta)$ for any β ?

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$$\Omega(n) + n^{2\beta-o(1)} = \Omega(n) + m^{2-o(1)}$$

Algorithm with time $\tilde{O}(n + m^2)$ exists!



More Parameters for LCS

more parameters have been studied for LCS since the 70s:

- $n = |x| = \max\{|x|, |y|\}$.. length of longer string
- $m = |y| = \min\{|x|, |y|\}$.. length of shorter string
- $L = \text{LCS}(x, y)$.. length of LCS
- $|\Sigma|$.. size of alphabet Σ
- $\Delta = n - L$.. number of deletions in x
- $\delta = m - L$.. number of deletions in y
- $M = \{(i, j) \mid x[i] = y[j]\}$.. number of *matching pairs*

	a	b	b	c	a	d
a	1	1	1	1	1	1
c	1	1	1	2	2	2
d	1	1	1	2	2	3
a	1	1	1	2	3	3
a	1	1	1	2	3	3
b	1	2	2	2	3	3
d	1	2	2	2	3	4



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$L = \text{LCS}(x, y)$.. length of LCS

$|\Sigma|$.. size of alphabet Σ

$\Delta = n - L$.. number of deletions in x

$\delta = m - L$.. number of deletions in y

$M = \{(i, j) \mid x[i] = y[j]\}$.. number of *matching pairs*

d .. number of *dominant pairs*

= “entry (i, j) is dominant if all entries to the top left of it are strictly smaller”

	a	b	b	c	a	d
a	1	1	1	1	1	1
c	1	1	1	2	2	2
d	1	1	1	2	2	3
a	1	1	1	2	3	3
a	1	1	1	2	3	3
b	1	2	2	2	3	3
d	1	2	2	2	3	4



Known Algorithms

$O(nm)$ [Wagner,Fischer'74]

$\tilde{O}(n + M)$ [Hunt,Szymanski'77]

$\tilde{O}(n + \delta m)$ [Hirschberg'77]

$\tilde{O}(n + Lm)$ [Hirschberg'77]

$\tilde{O}(n + d)$ [Apostolico'86]

$\tilde{O}(n + \delta\Delta)$ [Wu,Manber,Myers,Miller'90]

$n = \max\{ x , y \}$	$m = \min\{ x , y \}$
$L = \text{LCS}(x,y)$	$ \Sigma $ alphabet size
$\Delta = n - L$	M matching pairs
$\delta = m - L$	d dominating pairs

logfactor improvements:

[Masek,Paterson'80],
[Apostolico,Guerra'87],
[Eppstein,Galil,Giancarlo,
Italiano'92],
[Bille,Farach-Colton'08],
[Iliopoulos,Rahman'09]

What is the best possible algorithm for any “parameter setting”?



Parameter Settings

$n = \max\{ x , y \}$	$m = \min\{ x , y \}$
$L = \text{LCS}(x, y)$	$ \Sigma $ alphabet size
$\Delta = n - L$	M matching pairs
$\delta = m - L$	d dominating pairs

let $\alpha = (\alpha_m, \alpha_L, \alpha_\Sigma, \alpha_\Delta, \alpha_\delta, \alpha_M, \alpha_d) \in \mathbb{R}_{\geq 0}^7$

parameter setting $\text{LCS}(\alpha)$: is the LCS problem restricted to strings x, y with

$$(n = |x|) \quad m = \Theta(n^{\alpha_m}) \quad L = \Theta(n^{\alpha_L}) \quad |\Sigma| = \Theta(n^{\alpha_\Sigma}) \quad \text{etc.}$$

we always have $L \leq m$

so $\alpha_L > \alpha_m$ is contradictory

in this case $\text{LCS}(\alpha)$ has only finitely many instances = $\text{LCS}(\alpha)$ is **trivial**

We have to understand the interdependencies of parameters first!



Parameter Relations

$n = \max\{ x , y \}$	$m = \min\{ x , y \}$
$L = \text{LCS}(x, y)$	$ \Sigma $ alphabet size
$\Delta = n - L$	M matching pairs
$\delta = m - L$	d dominating pairs

For any strings x, y we have:

$$\left. \begin{array}{l} L \leq m \leq n \\ m \geq \delta \leq \Delta \leq n \\ d \leq M \end{array} \right\} \text{trivial}$$

$$\left. \begin{array}{l} |\Sigma| \leq m \\ M \geq n \end{array} \right\} \text{w.l.o.g. every symbol in } \Sigma \text{ appears in } x \text{ and in } y$$

$$L \leq d \leq Lm$$

$$|\Sigma| \leq d \leq L^2 |\Sigma|$$

$$d \leq 2L(\Delta + 1)$$

$$L^2 / |\Sigma| \leq M \leq 2Ln$$

complex dependencies of the parameters!



Known Algorithms

~~$O(nm)$~~

[Wagner,Fischer'74]

~~$\tilde{O}(n + M)$~~

[Hunt,Szymanski'77]

$\tilde{O}(n + \delta m)$

[Hirschberg'77]

~~$\tilde{O}(n + Lm)$~~

[Hirschberg'77]

$\tilde{O}(n + d)$

[Apostolico'86]

$\tilde{O}(n + \delta \Delta)$

[Wu,Manber,Myers,Miller'90]

$n = \max\{ x , y \}$	$m = \min\{ x , y \}$
$L = \text{LCS}(x, y)$	$ \Sigma $ alphabet size
$\Delta = n - L$	M matching pairs
$\delta = m - L$	d dominating pairs

parameter relations:

$$\delta \leq m \leq n$$

$$d \leq M$$

$$d \leq Lm$$

$$d \leq L^2 |\Sigma|$$

...

Best algorithm: $\tilde{O}(n + \min\{d, \delta m, \delta \Delta\})$



Parameter Settings

$$\begin{array}{ll} n = \max\{|x|, |y|\} & m = \min\{|x|, |y|\} \\ L = \text{LCS}(x, y) & |\Sigma| \text{ alphabet size} \\ \Delta = n - L & M \text{ matching pairs} \\ \delta = m - L & d \text{ dominating pairs} \end{array}$$

let $\alpha = (\alpha_m, \alpha_L, \alpha_\Sigma, \alpha_\Delta, \alpha_\delta, \alpha_M, \alpha_d) \in \mathbb{R}_{\geq 0}^7$

parameter setting $\text{LCS}(\alpha)$: is the LCS problem restricted to strings x, y with

$$(n = |x|) \quad m = \Theta(n^{\alpha_m}) \quad L = \Theta(n^{\alpha_L}) \quad |\Sigma| = \Theta(n^{\alpha_\Sigma}) \quad \text{etc.}$$

a parameter setting is **nontrivial** if it contains infinitely many instances

iff the target values $(n, n^{\alpha_m}, n^{\alpha_L}, \dots)$ satisfy our parameter relations (for $n \rightarrow \infty$)

What is the best possible running time $n^{f(\alpha)+o(1)}$ for any nontrivial $\text{LCS}(\alpha)$?



Matching Lower Bound

$$\begin{array}{ll} n = \max\{|x|, |y|\} & m = \min\{|x|, |y|\} \\ L = \text{LCS}(x, y) & |\Sigma| \text{ alphabet size} \\ \Delta = n - L & M \text{ matching pairs} \\ \delta = m - L & d \text{ dominating pairs} \end{array}$$

Best algorithm: $\tilde{O}(n + \min\{d, \delta m, \delta \Delta\})$

What is the best possible running time $n^{f(\alpha)+o(1)}$ for any nontrivial $\text{LCS}(\alpha)$?

Thm:

[B., Künnemann'16+]

Unless OVH fails, for any non-trivial parameter setting $\text{LCS}(\alpha)$
any algorithm takes time at least

$$\Omega(n) + \min\{d, \delta m, \delta \Delta\}^{1-o(1)}$$



III. Open Problems



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Major Open Problems

- 1) prove conditional lower bounds for **more types of problems**
- 2) relate **SAT, 3SUM, APSP** or show (more) barriers for such relations
- 3) advance **subquadratic approximation algorithms** and develop tools for **hardness of approximation**
- 4) explain gap between **deterministic / randomized** algorithms
- 5) **average case** hardness? **distributed** algorithm? other settings?

... this is a young field of research!



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k-Longest Common Subsequence (k-LCS)

given strings x_1, \dots, x_k , each of length at most n ,
compute longest string z that is a subsequence of all x_i

natural dynamic program $O(n^k)$

[Abboud, Backurs, V-Williams '15]

reduction SAT \rightarrow k-OV \rightarrow k-LCS yields lower bound of $\Omega(n^{k-\varepsilon})$

but only for strings over alphabets of size $\Omega(k)$

Open Problem: prove conditional lower bound $\Omega(n^{k-\varepsilon})$
for strings over alphabet size $O(1)$, or even 2

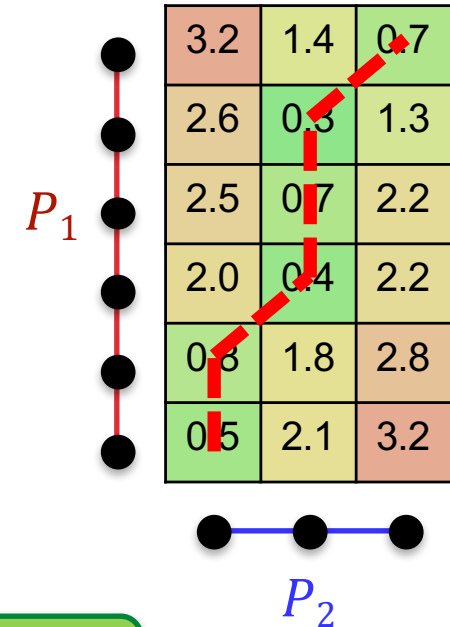
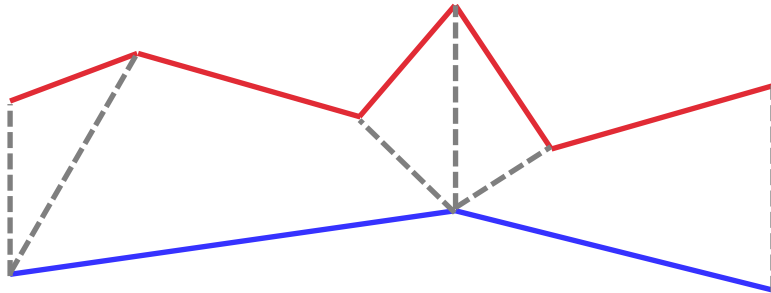
Open Problem: which log-factor improvements are possible?



Dynamic Time Warping

same setting as for Frechet distance: DTW is a similarity measure

for curves $P_1, P_2 =$ sequences over \mathbb{R}^2



natural dynamic programming algorithm: $O(n^2)$

$$T[i, j] = \text{DTW}(P_1[1..i], P_2[1..j])$$

$$T[i, j] = \|P_1[i] - P_2[j]\| +$$

= current distance

$$\min\{T[i - 1, j], T[i, j - 1], T[i - 1, j - 1]\}$$

last step in P_1

last step in P_2

last step in both



Dynamic Time Warping

same setting as for Frechet distance: DTW is a similarity measure
for curves $P_1, P_2 =$ sequences over \mathbb{R}^2

natural dynamic programming algorithm: $O(n^2)$

OV-hardness: lower bound $\Omega(n^{2-\varepsilon})$ [B.,Künnemann'15+, Abboud,Backurs,V-Williams'15]

slight improvement: $O(n^2 \log \log \log n / \log \log n)$ [Gold,Sharir'16]

Open Problem: log-factor improvement $n^2 / (\log n)^{\Omega(1)}$?

Open Problem: $n^{O(1)}$ –approximation in time $O(n^{2-\varepsilon})$?



3SUM

given sets A, B, C of n integers

are there $a \in A, b \in B, c \in C$ such that $a + b + c = 0$?

log-factor improvement: $O(n^2 \cdot \frac{(\log \log n)^2}{\log n})$

[Gronlund, Pettie'14]

we showed a simplified version: $O(n^2 \cdot \frac{\text{poly log log } n}{\sqrt{\log n}})$

Open Problem: $n^2 / 2^{\Omega(\sqrt{\log n})}$ algorithm?



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Dynamic Single Source Reachability

we have seen:

under OMv, no fully dynamic SSR with update $O(n^{1-\varepsilon})$, query $O(n^{2-\varepsilon})$

incremental SSR in total update $O(m)$, query $O(1)$

decremental SSR in DAGs in total update $O(m)$, query $O(1)$

decremental SSR in total update $O(mn)$, query $O(1)$

fastest known:

decremental SSR in total update $\tilde{O}(m\sqrt{n})$, query $\tilde{O}(1)$

Open Problem: faster decremental SSR? or lower bound?



IV. Outro



Oral Exam

on a day in September

(up to) 30 minutes

covers whole lecture and all exercises

please mark possible dates for you in this doodle:

<http://doodle.com/poll/v9bktxdrktv5w98e>



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End of Course

*“Fast Matrix Multiplication and Fast Fourier Transform
are the only non-trivial algorithmic tools that we have.”*

*“Whenever you design an algorithm, try to prove a matching
conditional lower bound to show optimality.”*



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