ground set S with n Elements finite set C of configurations two functions $tr, st : C \to 2^S$ with $tr(c) \cap st(c) = \emptyset$ for all $c \in C$ elements in tr(c) are the *triggers* of c (or "definers" of c) $\tau(c) = |tr(c)|$ elements in st(c) are the *stoppers* of c (or "killers" of c) $\sigma(c) = |st(c)|$

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 $S \dots n$ points on the real line





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$$\frac{c_3}{tr(c_3)} = \{a\} \quad st(c_3) = \emptyset$$



 $S \dots n$ points on the real line





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configurations are all bounded intervals defined by pairs of points in S and all unbounded intervals defined by a point in S



For $R \subset S$ consecutive points in R (plus leading and trailing unbounded interval) define the set $F_0(R)$ of active configurations in R

 $F_0(R)$ yields the sorted order of R $F_0(S)$ yields the sorted order of S



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 $F_0(R)$ yields the sorted order of R $F_0(S)$ yields the sorted order of S

 $f_0(R) = |R| + 1$ expected value $f_0(r) = r + 1$

d = 2



 $S \dots n$ points in the real plane in non-degenerate position configurations are all closed halfplanes bounded by lines that are defined by pairs of points in S





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 $tr(c_1) = \{4, 5\}$ $st(c_1) = \{3, 6, 7, 9\}$





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For $R \subset S$ consecutive points around the convex hull of R define the set $F_0(R)$ of active configurations in R

 $F_0(R)$ yields the convex hull of R $F_0(S)$ yields the convex hull of S

 $f_0(R) \leq |R|$ expected value $f_0(r) \leq r$

d = 2



Example 2': halfspaces

 $S \dots n$ points in 3-space in non-degenerate position configurations are all closed halfspaces bounded by planes that are defined by triples of points in S

For $R \subset S$ triples of points that span facets of the convex hull of R define the set $F_0(R)$ of active configurations in R

 $F_0(R)$ yields the convex hull of R $F_0(S)$ yields the convex hull of S

 $f_0(R) \le 2 \cdot |R| - 4$ expected value $f_0(r) \le O(r)$

d = 3



n segments K intersection points





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at most 3(n+K) + 1 trapezoids





 $S \dots n$ segments in the plane in non-degenerate position with K intersection points configurations are all trapezoids that appear in a trapezoidation of some subset of S

 Δ some trapezoid in trapezoidation for some $U \subset S$. $tr(\Delta)$ are all segments in U that intersect the boundary of Δ $st(\Delta)$ are all segments in S that intersect the interior of Δ



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 $tr(c) = \{1, 2, 3, 4\}$

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For $R \subset S$ the trapezoids in the trapezoidation of R define the set $F_0(R)$ of active configurations in R

 $F_0(R)$ yields the trapezoidation of R $F_0(S)$ yields trapezoidation of S

 $f_0(R) \le 3 \cdot (|R| + K_R) + 1$ and the expected value $f_0(r) \le O(r + \frac{r(r-1)}{n(n-1)}K)$

d = 4



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Typical problem: C is given implicitly; determine $F_0(S)$

Randomized Incremental Construction (RIC)



Configuration Spaces: Randomized Incremental Construction

Put S in random order s_1, \ldots, s_n . Let $S_r = \{s_1, \ldots, s_r\}$.

for r from 1 to n do compute $F_0(S_r)$ from $F_0(S_{r-1})$



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Typical additional bookkeeping: associate each $s \notin S_r$ with some $c \in F_0(S_r)$ with $s \in st(c)$ associate each $c \in F_0(S_r)$ with non-empty st(c) with one element in that set



RIC: strange quicksort



RIC: 2d convex hulls



RIC: 3d convex hulls



RIC: trapezoidations of segments



c becomes active during an enumeration of S if it is active for some "prefix" S_r . i small integer

 $X_i = \sum (\tau(c) + \sigma(c))^{\underline{i}}.$ $c \in C$ s.t. c becomes active during random enumeration of S

 $A_i = \operatorname{Ex}[X_i]$ typically measures the expected running time of an RIC algorithm.



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RIC Theorem:

$$A_i = O\left(d^i n^i \sum_{0 \le r \le n} f_0(r)/r^{i+1}\right)$$



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strange quicksort: $f_0(r) = r + 1 \implies A_1 = O(n \log n)$



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convex hull in the plane or in 3-space: : $f_0(r) = O(r) \implies A_1 = O(n \log n)$



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$$f_0(r) = O(r + \frac{r^2}{n^2}K) \implies A_1 = O(K + n\log n)$$



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RIC Lemma:

$$A_i \le d^{\underline{i+1}} n^{\underline{i}} \sum_{0 \le r \le n} f_0(r) / r^{\underline{i+1}}$$

with equality if the configuration space is uniform.



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 $\Pr(c \text{ is active at stage } r) = \Pr(c \text{ becomes active}) \cdot \frac{\binom{r}{b}\binom{n-r}{k}}{\binom{n}{b+k}}$

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$$\binom{A}{B}\binom{B}{C} = \binom{A}{C}\binom{A-C}{A-B} = \binom{A}{C}\binom{A-C}{B-C} \qquad \sum_{r}\binom{r-A-1}{B-A-1}\binom{N-r}{C} = \binom{N-A}{B+C-A}$$



Sampling Theorem

For integer $i \geq 0$ and $R \subseteq S$ define

$$B_i(R) = \sum_{c \text{ active for } R} \sigma(c)^{\underline{i}}$$

and let $B_i(r)$ be the expectation of $B_i(R)$ with R chosen uniformly at random from $\binom{S}{r}$.



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Lemma:

$$B_{i}(r) \leq \frac{(d+1)^{\overline{i+1}}}{(r+1)^{\overline{i+1}}} (n-r)^{\underline{i}} \sum_{0 \leq j \leq r} f_{0}(j)$$



Ingredients for the proof of the sampling Lemma

Same ingredients as for the RIC Lemma

it all reduces to showing that

$$\binom{r+i+1}{b+i+1}\binom{n-r-i}{k-i} \leq \sum_{0 \leq j \leq r} \binom{j}{b}\binom{n-j}{k}$$



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you argue this inequality by considering all binary strings of length n + 1 with exactly b + k + 1 digits '1' of which exactly b + i + 1 are in the first r + i + 1 positions



Sampling concentration Lemma

Lemma: Assuming that the number of configurations is $O(n^d)$ the following holds: If R is a random subset of S of size r then with probability at most 1/2 for each c that is active for R the number of stoppers $\sigma(c)$ is $O(\frac{n}{r} \log r)$.



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Proof sketch: consider configuration c with $\tau(c) = d$ and $\sigma(c) = k$. The probability that c is active for R is roughly

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which is $\leq \left(\frac{r}{n}\right)^d e^{-\frac{rk}{n}}$ By having $k > \alpha \frac{n}{r} \log r$ for sufficiently large α this is $O(1/n^d)$ and for $O(n^d)$ configurations this sums to less than 1/2.



Cuttings for lines

Cutting Lemma:

Let S be a set of n lines in the plane in non-degenerate position and let r be some number less than n.

In O(nr) expected time you can find a partition of the plane into $O(r^2)$ trapezoids so that each trapezoid is intersected by at most n/r of the lines in S.



Triangle range searching in the plane

Preprocess a set S of n points in the plane so that for any query triangle T you can quickly determine the points of S that are contained in T.







