Topics in Algorithmic Game Theory and Economics

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Max Planck Institute for Informatics (D1) Saarland Informatics Campus

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Lecture 11 Prophet Inequalities

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Goal: Select subset $S \in \mathcal{F}$ maximizing $w(S) = \sum_{e \in S} w(e)$.

With adversarial arrival order

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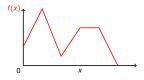
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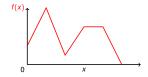
 $\int_0^\infty f(x)dx = 1.$ It then holds that $\mathbb{P}(X \le z) = \int_0^z f(x)dx$.

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Remark

All the results we discuss today hold for both continuous and discrete distributions, but sometimes need slightly different arguments.

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Adversary is non-adaptive if order is fixed after seeing all realizations.

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 - If $w_1 = 1/\epsilon$, then select e_1 (as $\frac{1}{\epsilon} > 1 + \delta$).
 - If $w_1 = 0$, reject e_1 and select e_2 .
- Worst-case arrival order is (e_2, e_1) .
 - We don't know realization w_1 , when deciding on element e_2 .
 - Nevertheless, it is (intuitively) optimal to select *e*₂.
 - Why? Deterministic value $w_2 = 1 + \delta > \mathbb{E}[X_1]$.
 - In expectation (of X_1), we cannot do better if we reject e_2 .

Let $E = \{e_1, e_2\}$ of which we may select at most one element. Let $1 > \epsilon, \delta > 0$, and assume that $\frac{1}{\epsilon} > 1 + \delta$. Distributions are given by:

$$w_1 \sim X_1 = \begin{cases} \frac{1}{\epsilon} & \text{with probability } \epsilon \\ 0 & \text{with probability } 1 - \epsilon \end{cases}$$
 (1)

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- Performance objective is formalized next.

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This is called a prophet inequality.

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Optimal algorithm A is to select e_2 (again, think about it).

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- Worst-case order is (e_2, e_1) with $\mathbb{E}_{(v_1, v_2)}[w(\mathcal{A}(\sigma, y_1, y_2))] = 1$.
- I.e., optimal algorithm only half as bad as prophet $(\alpha = \frac{1}{2})$.
- Also shows that, in general, we cannot hope for \mathcal{A} with $\alpha > \frac{1}{2}$, already in setting where we can select at most one (out of two) elements.

Selecting single element

Prophet Inequality with $\alpha = \frac{1}{2}$

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Median of distribution *X* is value *m* such that

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Example

Suppose we have uniform distribution over (continuous) interval [a, b]. Then $m = \frac{a+b}{2}$.

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• For i = 1, ..., m: If $w_{\sigma(i)} \ge T$, select $\sigma(i)$ and STOP.

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Theorem (Kleinberg and Weinberg, 2012)

The KW-algorithm selects an element e* with the property that

$$\mathbb{E}_{X_1,...,X_m}[w(e^*)] \geq \frac{1}{2} \cdot \mathbb{E}[\max_j X_j].$$

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It holds that

$$\mathbb{E}[X_{\tau}] = \int_0^T \mathbb{P}[X_{\tau} > x] dx + \int_T^{\infty} \mathbb{P}[X_{\tau} > x] dx$$

when all distributions X_i are continuous.

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See background material for discrete version of this claim:

$$\mathbb{E}_{X_1,...,X_m}[w(e^*)] \geq \frac{\mathbb{E}[\max_j X_j]}{2} \ \ (=T)$$

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when all distributions X_i are continuous.

See background material for discrete version of this claim:

$$\mathbb{E}[X] = \sum_{k=0}^{\infty} \mathbb{P}[X \ge k].$$

$$\mathbb{E}[X_{\tau}] = \int_0^T \mathbb{P}[X_{\tau} > x] dx + \int_T^{\infty} \mathbb{P}[X_{\tau} > x] dx, \quad T = \frac{\mathbb{E}[\max_j X_j]}{2}$$

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This completes the proof.



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 - Similar to what we saw for secretary problem.

Selecting indep. set from matroid $\mathcal{M} = (E, \mathcal{I})$ with arrival order σ .

Set $S = \emptyset$.

- For i = 1, ..., m, a realization $w_i \sim X_i$ is generated.
 - All realizations w_i are shown to the adversary.
- For i = 1, ..., m:
 - Adversary chooses $\sigma(i) \in E$, and reveals it and its weight w_i .
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where $OPT = \mathbb{E}_{(y_1,...,y_m) \sim X_1 \times \cdots \times X_m} [OPT(y_1,...,y_m)]$ is offline optimum.

Algorithm sets threshold in step *i* based on marginal contribution of $\sigma(i)$.

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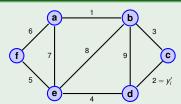
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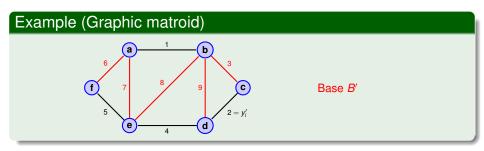
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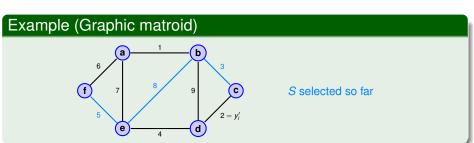
Example (Graphic matroid)



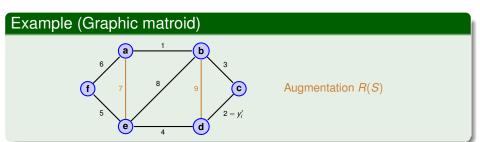
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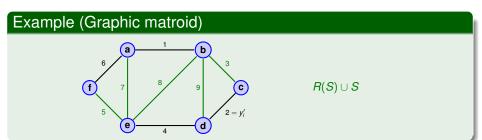
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KW-algorithm with initial $S = \emptyset$

For i = 1, ..., m: If $S \cup \{e_i\} \in \mathcal{I}$ do the following.

Set threshold

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Adaptive vs. non-adaptive threshold-based algorithms.

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- Feldman, Svensson and Zenklusen (2020) give such an example for so-called gammoids.
- They show that one can hope at best for a prophet inequality with

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Theorem (Babaioff et al. (2007), Rubinstein (2016))

There is no randomized algorithm that, for every downward-closed set system $\mathcal{F}=(\mathcal{E},\mathcal{I})$ with m elements having known weight distribution, obtains a prophet inequality with α better than

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Selecting single element

Sample-based threshold

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- Algorithms only using single sample from every X_i will be called single-sample algorithms.

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Every order-oblivious α -approximation for the secretary problem (with uniform random arrivals) gives rise to a single-sample prophet inequality with factor α (for worst-case arrival order).

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Corollary (AKW, 2014)

There is a single-sample $\alpha = \frac{1}{8}$ graphic matroid prophet inequality.

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• Proof uses the fact that both (offline) sample x_i and (online) realization w_i come from the same distribution X_i .

Prophet inequalities for I.I.D. distributions

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Theorem (Correa et al., 2018)

In case the online algorithm only has access to weights revealed so far (but not to common distribution X), there is a prophet inequality with $\alpha = \frac{1}{e}$ and this is best possible.

Secretary prophet inequalities

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- Also saw some other models (e.g., single-sample settings).