Topics in Algorithmic Game Theory and Economics

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Lecture 3 Congestion games II - Inefficiency of PNE

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Pure Nash equilibrium

We will focus on pure Nash equilibria in congestion games.

Definition (Pure Nash equilibrium (PNE))

A strategy profile $s \in \times_i S_i$ is a pure Nash equilibrium if for every $i \in N$,

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From Lecture 2:

- Computing PNE is PLS-complete problem in general.
- PNE can be computed efficiently in special case of symmetric network congestion games.
- Better response dynamics converge rapidly in singleton congestion games.

Inefficiency of equilibria

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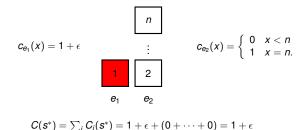
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$$C(s) = \sum_i C_i(s) = 1 + (1 + \dots + 1) = n$$

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Are there classes of games where PoA/PoS is constant (for any n)? Yes, if we make assumptions on the cost functions.

Polynomial cost functions are of the form

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Etc...

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Remark

For polynomials of degree at most *d*, a tight bound is known as well. It grows roughly like $d^{d(1-o(1))}$.

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Rearranging terms and exploiting that $\mu < 1$ proves the claim.

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The robust price of anarchy of a strategic game Γ is defined as

$$RPoA(\Gamma) = \inf \left\{ \frac{\lambda}{1-\mu} : \Gamma \text{ is } (\lambda,\mu) \text{-smooth with } \mu < 1 \right\}$$

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RPoA automatically extends to other equilibria types in hierarchy.
 Mixed, correlated and coarse correlated equilibria.

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- Assume (w.l.o.g.) that $c_e(x) = x$ for every $e \in E$.
- Write $x_e = x_e(s)$ and $x_e^* = x_e(s^*)$.

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Fact

Let α and β be two non-negative integers. Then

$$\alpha(\beta+1) \leq \frac{5}{3}\alpha^2 + \frac{1}{3}\beta^2.$$

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PoA lower bound for affine congestion games

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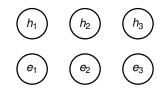
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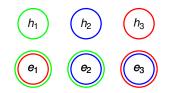
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Pure Nash equilibrium *s* Every player *i* plays $\{e_{i-1}, e_{i+1}, h_{i+1}\}$, which gives C(s) = 15.

Definition

Γ is called (λ, μ) -smooth if for any two strategy profiles $s, s^* \in \times_i S_i$,

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Definition (PoA, general)

For $EQ \in \{PNE, MNE, CE, CCE\}$, we define

$$\mathsf{PoA}_{EQ}(\Gamma) = \frac{\max_{\sigma \in \mathsf{EQ}} \mathbb{E}_{s \sim \sigma} \left[\mathcal{C}(s) \right]}{\min_{t \in \times_i \mathcal{S}_i} \mathcal{C}(t)}$$

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Theorem (Extension)

If the game Γ is (λ, μ) -smooth, then $RPoA_{EQ}(\Gamma) \leq \lambda/(1-\mu)$.

Definition (Coarse correlated equilibrium (CCE))

A distribution σ on $\times_i S_i$ is a coarse correlated equilibrium if for every $i \in N$, and every unilateral deviation $s'_i \in S_i$, it holds that

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Proof (extension theorem): Let s be CCE and s^* social optimum. Then

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The smoothness framework cannot always be applied. For example, a tight bound on the Price of Anarchy of 4/3 is known for class of symmetric singleton congestion games, but this bound does not extend to more general equilibrium types.

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• Same is true for Price of Stability bounds (up next).

Price of Stability for affine congestion game Γ

$$\mathsf{PoS}(\Gamma) = \frac{\min_{s \in \mathsf{PNE}} C(s)}{\min_{t \in \times_i S_i} C(t)}$$

For bounding the PoS, we need to do something else than just use the inequalities defining a PNE.

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We have seen that PNEs are local minima of Rosenthal's potential (w.r.t the unilateral deviation neighbourhood). Do some local minima have better social cost than others?

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• Strategy profile *s* is global minimizer if $\Phi(s) \leq \Phi(t)$ for all $t \in \times_i S_i$.

Potential function approach for bounding PoS

Theorem

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Remark

Can be improved to tight bound of $1 + 1/\sqrt{3} \approx 1.577$.

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PNE inequalities

$$\sum_{e \in E} x_e^2 = \sum_i C_i(s) \le \sum_i C_i(s_i^*, s_{-i}) \le \sum_{e \in E} x_e^*(x_e + 1)$$

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$$\frac{1}{2}\sum_{e \in E} x_e(x_e + 1) = \Phi(s) \le \Phi(s^*) = \frac{1}{2}\sum_{e \in E} x_e^*(x_e^* + 1)$$

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Overview for affine congestion games

Theorem

Price of Anarchy for affine congestion games is 5/2.

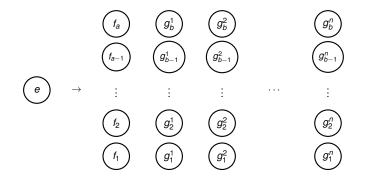
- Relatively simple lower bound construction showing tightness.
- Proof extends to other equilibrium types in hierarchy by means of (λ, μ) -smoothness technique.

Theorem

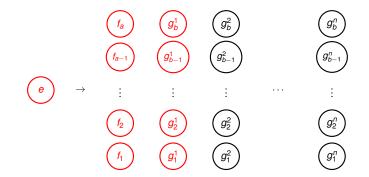
Price of Stability for affine congestion games is $1 + 1/\sqrt{3} \approx 1.577$.

- Tightness examples are more involved.
- Proof does not extend to other equilibrium types in hierarchy.

Suppose that $c_e(x) = a_e x + b_e$ with $a_e, b_e \in \mathbb{N}$. (Same works for \mathbb{Q} .) • We write $a = a_e, b = b_e$.

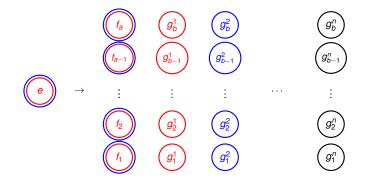


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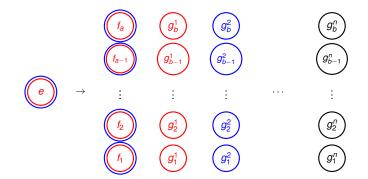
If player *i* uses *e* in some of its strategies, replace it by set $K_i(e) = \{f_1, \dots, f_a, g_1^i, \dots, g_b^i\}.$

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Cost incurred on resources $K_i(e)$ is precisely $ax_e + b$ if load is x_e .